## **Simple Harmonic Motion**

Hooke's law: F = -kx ([k] = N/m)

⇒ the – sign indicates that the direction of the force is opposite the displacement

Frequency:  $f = \frac{1}{T}$  ([f] = Hz)

Period:  $T = \frac{1}{f}$  ([T] = s)

## Simple Harmonic Motion:

⇒ for an object oscillating in simple harmonic motion:

$$x = A\cos\omega t$$
  $x_{\text{max}} = A$   
 $v = -A\omega\sin\omega t$   $v_{\text{max}} = A\omega$ 

$$a = -A\omega^2 \cos \omega t \qquad a_{\text{max}} = A\omega^2$$

$$\omega = 2\pi f = \frac{2\pi}{T}$$

Note: 
$$v = 0$$
 at  $x = \underline{+}A$ ;  $v = v_{max}$  at  $x = 0$   $a = 0$  when  $x = 0$ ;  $a = a_{max}$  at  $x = \underline{+}A$ 

⇒ for a mass m oscillating on a spring with spring constant k:

$$\omega = \sqrt{\frac{k}{m}}$$
  $f = \frac{1}{2\pi} \sqrt{\frac{k}{m}}$   $T = 2\pi \sqrt{\frac{m}{k}}$ 

Elastic Potential Energy:  $PE = \frac{1}{2}kx^2$ 

Conservation of Energy:  $\frac{1}{2}mv_0^2 + mgh_0 + \frac{1}{2}kx_0^2 = \frac{1}{2}mv_f^2 + mgh_f + \frac{1}{2}kx_f^2$ 

## Simple Pendulum:

⇒ for a simple pendulum (for small angles):

$$\omega = \sqrt{\frac{g}{L}}$$
  $f = \frac{1}{2\pi} \sqrt{\frac{g}{L}}$   $T = 2\pi \sqrt{\frac{L}{g}}$